

# LogiCORE IP FIR Compiler v6.3 Bit Accurate C Model

## *User Guide*

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## Revision History

The following table shows the revision history for this document.

| Date     | Version | Revision  |
|----------|---------|---|
| 10/19/11 | 1.0     | Initial Xilinx release.   |
| 1/18/12  | 1.1     | MATLAB MEX function added   |
| 4/24/12  | 1.2     | Updated for ISE Release 14.1. CORE Generator delivery of C Model. |

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# Introduction

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The Xilinx® LogiCORE™ IP FIR Compiler v6.3 core bit accurate C model is a self-contained, linkable, shared library that models the functionality of this core with finite precision arithmetic. This model provides a bit accurate representation of the various modes of the FIR Compiler v6.3 core, and it is suitable for inclusion in a larger framework for system-level simulation or core-specific verification.

## Features

- Bit accurate with FIR Compiler v6.3 core
- Available for 32-bit and 64-bit Linux platforms
- Available for 32-bit and 64-bit Windows platforms
- Supports all features of the FIR Compiler v6.3 core
- Designed for integration into a larger system model
- Example C code showing how to use the C model functions
- MEX function and class to support MATLAB® software integration

## Overview

This user guide provides information about the Xilinx LogiCORE IP FIR Compiler v6.3 bit accurate C model for 32-bit and 64-bit Linux, and 32-bit and 64-bit Windows platforms.

The model consists of a set of C functions that reside in a shared library. Example C code is provided to demonstrate how these functions form the interface to the C model. Full details of this interface are given in [Chapter 3](#) of this document.

The model is bit accurate but not cycle-accurate; it performs exactly the same operations as the core. However, it does not model the core's latency or its interface signals.

## Feedback

Xilinx welcomes comments and suggestions about the FIR Compiler v6.3 core and the accompanying documentation.

### FIR Compiler v6.3 Bit Accurate C Model and IP Core

For comments or suggestions about the FIR Compiler v6.3 core and bit accurate C model, submit a WebCase from [www.xilinx.com/support/clearxpress/websupport.htm](http://www.xilinx.com/support/clearxpress/websupport.htm). Be sure to include the following information:

- Product name
- Core version number
- Explanation of your comments

## Documentation

For comments or suggestions about the FIR Compiler v6.3 core documentation, submit a WebCase from [www.xilinx.com/support/clearxpress/websupport.htm](http://www.xilinx.com/support/clearxpress/websupport.htm). Include the following information:

- Document title
- Document number
- Page number(s) to which your comments refer
- Explanation of your comments

## User Instructions

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The C model ZIP files are delivered in the `cmodel` directory of a generated core or can be accessed from the FIR Compiler [product page](#).

### Unpacking and Model Contents

There are separate ZIP files containing all the files necessary for use with a specific computing platform. Each ZIP file contains:

- The C model shared library
- Multiple Precision Integers and Rationals (MPIR) [\[Ref 2\]](#) shared libraries and header files.
- The C model header file
- The example code showing customers how to call the C model
- Documentation

**Note:** The C model uses MPIR libraries, which is provided in the ZIP files. MPIR is an interface-compatible version of the GNU Multiple Precision (GMP) [\[Ref 3\]](#) library, with greater support for Windows platforms. MPIR has been compiled using its GMP compatibility option, so the MPIR library and header file use GMP file names.

*Table 2-1: Example C Model ZIP File Contents - Linux*

| File  | Description  |
|---|--|
| <code>fir_compiler_v6_3_bitacc_cmodel.h</code>        | Header file which defines the C model API          |
| <code>libIp_fir_compiler_v6_3_bitacc_cmodel.so</code> | Model shared object library                        |
| <code>libstlport.so.5.1</code>                        | STL portability library                            |
| <code>libgmp.so.7</code>                              | MPIR library, used by the C model                  |
| <code>libgmpxx.so.1</code>                            | MPIR Class library, used internally by the C model |
| <code>gmp.h</code>                                    | MPIR header file, used by the C model              |
| <code>run_bitacc_cmodel.c</code>                      | Example program for calling the C model            |
| <code>README.txt</code>                               | Release notes                                      |
| <code>ug853_fir_compiler_cmodel.pdf</code>            | This user guide                                    |
| <code>fir_compiler_v6_3_bitacc_mex.cpp</code>         | MATLAB MEX function source                         |
| <code>make_fir_compiler_v6_3_mex.m</code>             | MATLAB MEX function compilation script             |

**Table 2-1: Example C Model ZIP File Contents - Linux (Cont'd)**

| File                        | Description                         |
|-----------------------------|-------------------------------------|
| run_fir_compiler_v6_3_mex.m | MATLAB MEX function example script  |
| @fir_compiler_v6_3_bitacc   | MATLAB MEX function class directory |

**Table 2-2: Example C Model ZIP File Contents - Windows**

| File                                      | Description                               |
|---|---|
| fir_compiler_v6_3_bitacc_cmodel.h         | Header file which defines the C model API |
| libIp_fir_compiler_v6_3_bitacc_cmodel.dll | Model dynamically linked library          |
| libIp_fir_compiler_v6_3_bitacc_cmodel.lib | Model .lib file for compiling             |
| stlport5.1.dll                            | STL portability library                   |
| libgmp.dll                                | MPIR library, used by the C model         |
| libgmp.lib                                | MPIR .lib file for compiling              |
| gmp.h                                     | MPIR header file, used by the C model     |
| run_bitacc_cmodel.c                       | Example program for calling the C model   |
| README.txt                                | Release notes                             |
| ug812_fir_compiler_cmodel.pdf             | This user guide                           |
| fir_compiler_v6_3_bitacc_mex.cpp          | MATLAB MEX function source                |
| make_fir_compiler_v6_3_mex.m              | MATLAB MEX function compilation script    |
| run_fir_compiler_v6_3_mex.m               | MATLAB MEX function example script        |
| @fir_compiler_v6_3_bitacc                 | MATLAB MEX function class directory       |

## Installation

### Linux

- Unpack the contents of the ZIP file.
- Ensure that the directory where the `libIp_fir_compiler_v6_3_bitacc_cmodel.so`, `libgmp.so.7` and `libgmpxx.so.1` files reside is included in the path of the environment variable `LD_LIBRARY_PATH`.

### Windows

- Unpack the contents of the ZIP file.
- Ensure that the directory where the `libIp_fir_compiler_v6_3_bitacc_cmodel.dll` and `libgmp.dll` files reside is
  - a. included in the path of the environment variable `PATH` or
  - b. the directory in which the executable that calls the C model is run.

## FIR Compiler v6.3 Bit Accurate C Model

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### C Model Interface

The Application Programming Interface (API) of the C model is defined in the header file `fir_compiler_v6_3_bitacc_cmodel.h`. The interface consists of data structures and functions as described in the sections:

- [Constants](#)
- [Type Definitions](#)
- [Dynamic Arrays](#)
- [Structures](#)
- [Functions](#)

An example C file, `run_bitacc_cmodel.c`, is included with the C libraries. This file demonstrates how to call the C model.

### Constants

Table 3-1: Constants

| Name                    | Value |
|-------------------------|-------|
| <b>Error codes</b>      |       |
| XIP_STATUS_OK           | 0     |
| XIP_STATUS_ERROR        | 1     |
| <b>Filter Types</b>     |       |
| XIP_FIR_SINGLE_RATE     | 0     |
| XIP_FIR_INTERPOLATION   | 1     |
| XIP_FIR_DECIMATION      | 2     |
| XIP_FIR_HILBERT         | 3     |
| XIP_FIR_INTERPOLATED    | 4     |
| <b>Rate Change</b>      |       |
| XIP_FIR_INTEGER_RATE    | 0     |
| XIP_FIR_FRACTIONAL_RATE | 1     |

Table 3-1: Constants (Cont'd)

| Name                           | Value |
|--------------------------------|-------|
| <b>Channel Sequence</b>        |       |
| XIP_FIR_BASIC_CHAN_SEQ         | 0     |
| XIP_FIR_ADVANCED_CHAN_SEQ      | 1     |
| <b>Quantization</b>            |       |
| XIP_FIR_INTEGER_COEFF          | 0     |
| XIP_FIR_QUANTIZED_ONLY         | 1     |
| XIP_FIR_MAXIMIZE_DYNAMIC_RANGE | 2     |
| <b>Output Rounding</b>         |       |
| XIP_FIR_FULL_PRECISION         | 0     |
| XIP_FIR_TRUNCATE_LSBS          | 1     |
| XIP_FIR_SYMMETRIC_ZERO         | 2     |
| XIP_FIR_SYMMETRIC_INF          | 3     |
| XIP_FIR_CONVERGENT_EVEN        | 4     |
| XIP_FIR_CONVERGENT_ODD         | 5     |
| XIP_FIR_NON_SYMMETRIC_DOWN     | 6     |
| XIP_FIR_NON_SYMMETRIC_UP       | 7     |
| <b>Configuration Method</b>    |       |
| XIP_FIR_CONFIG_SINGLE          | 0     |
| XIP_FIR_CONFIG_BY_CHANNEL      | 1     |

## Type Definitions

Table 3-2: Type Definitions

| Field Name                                | Description  |
|---|--|
| <b>General types</b>                      |  |
| typedef double xip_real                   | Scalar type alias  |
| typedef unsigned integer xip_uint         | Integer type alias   |
| typedef struct xip_complex                | Complex data type  |
| typedef mpz_t xip_mpz                     | MPIR [Ref 2] integer type alias                                |
| typedef struct xip_mpz_complex            | Complex type based on xip_mpz                                  |
| typedef int xip_status                    | Result code from API functions                                 |
| typedef struct _xip_fir_v6_3 xip_fir_v6_3 | Handle type to refer to an instance of the model               |
| typedef enum xip_fir_v6_3_pattern         | Defines enumerated values for all the advance channel patterns |

Table 3-2: Type Definitions (Cont'd)

| Field Name   | Description   |
|--|---|
| <b>Handler function signatures</b>   |   |
| <code>typedef void (*xip_msg_handler)(void* handle, int error, const char* msg)</code>                       | Interface to a message handler function                   |
| <code>typedef void (*xip_array_real_handler)(const xip_array_real* data, void* handle, void* opt_arg)</code> | Interface to data packet handler function                 |
| <b>Structures</b>  |   |
| <code>typedef struct xip_fir_v6_3_config</code>  | Model configuration structure, <a href="#">Table 3-4</a>  |
| <code>typedef struct xip_fir_v6_3_cnfg_packet</code>   | Configuration packet structure, <a href="#">Table 3-5</a> |
| <code>typedef struct xip_fir_v6_3_rld_packet</code>  | Reload packet structure, <a href="#">Table 3-6</a>        |
| <b>Array types</b>   |   |
| <code>typedef struct xip_array_uint</code>   | See <a href="#">Dynamic Arrays</a>                        |
| <code>typedef struct xip_array_real</code>   |   |
| <code>typedef struct xip_array_complex</code>  |   |
| <code>typedef struct xip_array_mpz</code>  |   |

## Dynamic Arrays

The C model represents input and output data using multi-dimensional dynamic arrays. The `xip_array_<type>` structure is used to specify a multi-dimensional dynamic array containing elements of type `xip_<type>`. A number of utility functions are provided that allow creation, allocation and destruction of array instances.

For each array type, the `DECLARE_XIP_ARRAY(<type>)` macro can be used to declare the structure and utility function prototypes. The C model header already contains declarations for the following array types:

- `xip_array_real` for arrays of `xip_real`
- `xip_array_complex` for arrays of `xip_complex`
- `xip_array_uint` for arrays of `xip_uint`
- `xip_array_mpz` for arrays of `xip_mpz`
- `xip_array_mpz_complex` for arrays of `xip_mpz_complex`

The utility functions for each array type can be defined using the `DEFINE_XIP_ARRAY(<type>)` macro. The utility function must be defined somewhere within user code before the functions can be used; see the `run_bitacc_cmodel.c` file for examples.

Further utility functions, specific to the FIR Compiler C Model, can be declared and defined using the `DECLARE_FIR_XIP_ARRAY(<type>)` and `DEFINE_FIR_XIP_ARRAY(<type>)` macros. The C model header already contains declarations for the following array types:

- `xip_array_real`
- `xip_array_complex`

- xip\_array\_mpz
- xip\_array\_mpz\_complex

## Structure

The `xip_array_<type>` structure is used to specify a multi-dimensional array of data with type `<type>`. The content is summarized in [Table 3-3](#).

**Table 3-3: xip\_array\_<type>**

| Field Name    | Type         | Description  |
|---------------|--------------|--|
| data          | xip_<type>*  | Pointer to array of data   |
| data_size     | size_t       | Current number of elements in the data array   |
| data_capacity | size_t       | Max number of elements in the data array   |
| dim           | size_t*      | Pointer to dimension array   |
| dim_size      | size_t       | Current number of elements in the dimension array, dim   |
| dim_capacity  | size_t       | Max number of elements in dim array  |
| owner         | unsigned int | Ownership control. A value of 0 indicates that the structure and associated memory (for the data and dim fields) is allocated and owned by the <code>xip_array_&lt;type&gt;_*</code> functions, in which case the model can automatically resize arrays as required. Any other value indicates that the memory is owned by the user, and the model must report an error if an array is of insufficient capacity. |

This data structure is defined for types:

- xip\_real
- xip\_complex
- xip\_uint
- xip\_mpz
- xip\_mpz\_complex

## General Functions

### Create Array

```
xip_array_<type>*
xip_array_<type>_create();
```

This function allocates and initializes an empty array for holding values of type `<type>`. The function returns a pointer to the created structure, or null if the structure cannot be created. The structure fields are all initialized to zero indicating an empty array, with ownership associated with the `xip_array_<type>_*` functions.

### Reserve Data Memory

```
xip_status
xip_array_<type>_reserve_data(
    xip_array_<type>* p,
    size_t max_nels
);
```

This function ensures that array `p` has sufficient space to store up to `max_nels` elements of data. If the current `data_capacity` is insufficient and the current owner is zero, the function attempts to allocate or reallocate space to meet the request. The function returns `XIP_STATUS_OK` if the array capacity is now sufficient or `XIP_STATUS_ERROR` if memory could not be allocated.

**Note:** This function does not change the data or dimensions held within the array in any way; the contents of the array after calling the function are equivalent to the contents before calling the function, even if memory is reallocated. Also, this function never reduces memory allocation; use `xip_array_<type>_destroy` to release memory.

### Reserve Dimension Memory

```
xip_status
xip_array_<type>_reserve_dim(
    xip_array_<type>* p,
    size_t max_nels
);
```

This function ensures that array `p` has sufficient space to store up to `max_ndims` dimensions. If the current `dim_capacity` is insufficient and the current owner is zero, the function attempts to allocate or reallocate space to meet the request. The function returns `XIP_STATUS_OK` if the array capacity is now sufficient or `XIP_STATUS_ERROR` if memory could not be allocated.

**Note:** This function does not change the data or dimensions held within the array in any way; the contents of the array after calling the function are equivalent to the contents before calling the function, even if memory is reallocated. Also, this function never reduces memory allocation; use `xip_array_<type>_destroy` to release memory.

### Destroy Array

```
xip_array_<type>*
xip_array_<type>_create(
    xip_array_<type>* p
);
```

This function attempts to release all memory associated with array `p`. If the owner field is zero, the function releases the memory associated with `data`, `dim` and `p`, and returns null indicating success. If owner is non-zero the function returns `p`, indicating failure.

## FIR Compiler Specific Functions

The following functions have been added to aid the use of the array types with the FIR Compiler C Model and, specifically, the advanced channel patterns.

### Set Channel

```
xip_status
xip_array_<type>_set_chan(
    xip_array_<type>* p
    const <type> value,
    size_t path,
    size_t chan,
    size_t index
    xip_fir_v6_3_pattern pattern
);
```

This function maps an array index for one channel, specified by `path` and `chan`, onto the 3-D structure of `xip_array_<type>` structure expected by the model's `xip_fir_v6_3_data_send` (see [Send DATA Packet, page 20](#)) and `xip_fir_v6_3_data_get` (see [Get DATA Packet, page 22](#)) functions.

This function should be particularly useful for the Advanced Interleaved Channels feature; see [\[Ref 1\]](#) for details of this feature, where locations in the input array are remapped to duplicate entries for some channels. [Figure 3-2](#) illustrates this requirement.

`pattern` should be set to `P_BASIC` for a Basic Interleaved Channel model configuration and set to the current pattern ID for an Advanced Interleaved Channel model configuration. See [\[Ref 1\]](#) for a list of all the supported patterns and see `fir_compiler_v6_3_bitacc_cmodel.h` for the enumerated pattern IDs.

**Note:** If the value of `index` exceeds the current capacity (`data_capacity`) of `p` then the function issues a `XIP_STATUS_ERROR`. If the value of `index` exceeds number of elements (`data_size`) of `p` then the function sets the new size of the array.

### Get Channel

```
xip_status
xip_array_<type>_get_chan(
    xip_array_<type>* p
    <type>* value,
    size_t path,
    size_t chan,
    size_t index
    xip_fir_v6_3_pattern pattern
);
```

This function is the reciprocal of the `xip_array_<type>_set_chan` function and extracts an individual channel's value for a given index, path and channel. The function issues an `XIP_STATUS_ERROR` if the index exceeds the array capacity or size.

## Structures

The `xip_fir_v6_3_config` structure contains all parameters that affect the filter configuration. Most are duplicates of the core's XCO parameters. The model's filter coefficients are provided using the `coeff` field and are quantized (if specified) in the same manner as by the core GUI.

Table 3-4: `xip_fir_v6_3_config`

| Field Name               | Type                     | Description  |
|--------------------------|--------------------------|--|
| <code>name</code>        | <code>const char*</code> |  |
| <code>filter_type</code> | unsigned int             | Select from:<br><code>XIP_FIR_SINGLE_RATE</code><br><code>XIP_FIR_INTERPOLATION</code><br><code>XIP_FIR_DECIMATION</code><br><code>XIP_FIR_HILBERT</code><br><code>XIP_FIR_INTERPOLATED</code> |
| <code>rate_change</code> | unsigned int             | Select from:<br><code>XIP_FIR_INTEGER_RATE</code><br><code>XIP_FIR_FRACTIONAL_RATE</code>  |
| <code>interp_rate</code> | unsigned int             | Specifies the interpolation (or up-sampling) factor  |

Table 3-4: xip\_fir\_v6\_3\_config (Cont'd)

| Field Name        | Type                 | Description  |
|-------------------|----------------------|--|
| decim_rate        | unsigned int         | Specifies the decimation (or down-sampling) factor   |
| zero_pack_factor  | unsigned int         | Specifies the zero packing factor for Interpolated filters   |
| coeff             | const double*        | Pointer to coefficient array   |
| coeff_padding     | unsigned int         | Specifies the amount of zero padding added to the front of the filter.<br><b>Note:</b> The core GUI reports this value for a given core configuration. |
| num_coefs         | unsigned int         | Specifies the number of coefficients in one filter   |
| coeff_sets        | unsigned int         | Specifies the number of coefficient sets in the coeff array  |
| reloadable        | unsigned int         | Specifies if the coefficients are reloadable; 0 = No, 1 = Yes  |
| is_halfband       | unsigned int         | Specifies if halfband coefficients have been specified; 0 = No, 1 = Yes  |
| quantization      | unsigned int         | Select from:<br>XIP_FIR_INTEGER_COEFF<br>XIP_FIR_QUANTIZED_ONLY<br>XIP_FIR_MAXIMIZE_DYNAMIC_RANGE  |
| coeff_width       | unsigned int         | The model uses these parameters, if requested, to quantize the supplied coefficients   |
| coeff_fract_width | unsigned int         |  |
| chan_seq          | unsigned int         | Select from:<br>XIP_FIR_BASIC_CHAN_SEQ<br>XIP_FIR_ADVANCED_CHAN_SEQ  |
| num_channels      | unsigned int         | Specifies the number of data channels supported  |
| init_pattern      | xip_fir_v6_3_pattern | Specifies the initial channel pattern used by the model when Advanced Interleaved Channels have been selected  |
| num_paths         | unsigned int         | Specifies the number of data paths supported   |
| data_width        | unsigned int         | The model uses these parameters to quantize the model's input samples  |
| data_fract_width  | unsigned int         |  |

Table 3-4: xip\_fir\_v6\_3\_config (Cont'd)

| Field Name           | Type         | Description   |
|----------------------|--------------|---|
| output_rounding_mode | unsigned int | Select from:<br>XIP_FIR_FULL_PRECISION<br>XIP_FIR_TRUNCATE_LSBS<br>XIP_FIR_SYMMETRIC_ZERO<br>XIP_FIR_SYMMETRIC_INF<br>XIP_FIR_CONVERGENT_EVEN<br>XIP_FIR_CONVERGENT_ODD<br>XIP_FIR_NON_SYMMETRIC_DOWN<br>XIP_FIR_NON_SYMMETRIC_UP |
| output_width         | unsigned int | Ignored when XIP_FIR_FULL_PRECISION   |
| output_fract_width   | unsigned int | <b>READ ONLY</b><br>Provides the number of fractional bits present in the output word   |
| config_method        | unsigned int | Select from:<br>XIP_FIR_CONFIG_SINGLE<br>XIP_FIR_CONFIG_BY_CHANNEL  |

The `xip_fir_v6_3_cnfg_packet` structure is supplied to the `xip_fir_v6_3_config_send` function (see [Send CONFIG Packet, page 20](#)) to update the channel pattern and coefficient set used by the model.

Table 3-5: xip\_fir\_v6\_3\_cnfg\_packet

| Field Name | Type                              | Description   |
|------------|-----------------------------------|---|
| chanpat    | <code>xip_fir_v6_3_pattern</code> | Specifies the Advanced Interleaved Channel pattern to be used   |
| fsel       | <code>xip_array_uint*</code>      | Filter set to use, 1-D array; specifies one value for all channels (XIP_FIR_CONFIG_SINGLE) or individually for each interleaved channel (XIP_FIR_CONFIG_BY_CHANNEL) |

The `xip_fir_v6_3_rld_packet` structure is supplied to the `xip_fir_v6_3_reload_send` function (see [Send RELOAD Packet, page 20](#)) to update a given coefficient set with new filter coefficients. As with the core, a configuration packet must be processed by the model to apply any pending reload packets.

Table 3-6: xip\_fir\_v6\_3\_rld\_packet

| Field Name | Type                         | Description  |
|------------|------------------------------|--|
| fsel       | Int                          | Filter set to reload   |
| coeff      | <code>xip_array_real*</code> | Pointer to an array containing the new coefficients to be loaded, 1-D array. |

## Functions

### Model Configuration Functions

#### Get Version

```
const char* xip_fir_v6_3_get_version(void);
```

The function returns a string describing the version of the model.

#### Get Default Configuration

```
xip_status  
xip_fir_v6_3_get_default_config(  
    xip_fir_v6_3_config* config  
)
```

This function populates the `xip_fir_v6_3_config` configuration structure pointed to by `config` with the default configuration of the FIR Compiler v6.3 core.

#### Create Model Object

```
xip_fir_v6_3  
xip_fir_v6_3_create(  
    const xip_fir_v6_3_config* config,  
    xip_msg_handler msg_handler,  
    void* msg_handle  
)
```

This function creates a new model instance, based on the configuration data pointed to by `config`.

The `msg_handler` argument is a pointer to a function taking three arguments as previously defined in [Type Definitions](#). This function pointer is retained by the model object and is called whenever the model wishes to issue a note, warning or error message. Its arguments are:

1. A generic pointer (void\*). This is always the value that was passed in as the `msg_handle` argument to the create function.
2. An integer (int) indicating whether the message is an error (1) or a note or warning (0).
3. The message string itself.

If the `handler` argument is a null pointer, then the C model outputs no messages at all. Using this mechanism, you may choose whether to output messages to the console, log them to a file or ignore them completely.

The `create` function returns a pointer to the newly created object. If the object cannot be created, then a diagnostic error message is emitted using the supplied handler function (if any) and a null pointer is returned.

If the data and coefficient widths, number of coefficients and output precision result in an output precision greater than supported by the double (`xip_real`) data type then the model uses the `mpz_t` data type [Ref 2] (`xip_mpz`) and issues a warning indicating this requirement when this function is executed.

#### Get Model Configuration

```
xip_status  
xip_fir_v6_3_get_config (  
    xip_fir_v6_3* model,  
    xip_fir_v6_3_config* config  
)
```

This function returns the full configuration of the model. The function is intended to be primarily used to determine the output width and output fractional width of the model.

**Note:** The coeff pointer of the returned `xip_fir_v6_3_config` structure is set to NULL.

### Reset Model Object

```
xip_status
xip_fir_v6_3_reset(
    xip_fir_v6_3* model
);
```

This function resets in the internal state of the FIR Compiler model object pointed to by `model`. A reset causes all data and pending configuration packets to be cleared from the model. As per the core, any pending reload packets are retained.

### Destroy Model Object

```
xip_status
xip_fir_v6_3_destroy(
    xip_fir_v6_3* model
);
```

This function deallocates the model object pointed to by `model`.

Any system resources or memory belonging to the model object are released on return from this function. The model object becomes undefined, and any further attempt to use it is an error.

### Set Output Data Array

```
xip_status
xip_fir_v6_3_set_data_sink(
    xip_fir_v6_3* model,
    xip_array_real* data,
    xip_array_complex* cmplx_data
);
xip_status
xip_fir_v6_3_set_data_sink_mpz(
    xip_fir_v6_3* model,
    xip_array_mpz* data,
    xip_array_mpz_complex* cmplx_data
);
```

This function registers an array (the data sink), pointed to by `data` or `cmplx_data`, to push the generated filter output when the `xip_fir_v6_3_data_send` function is called. Only `data` or `cmplx_data` may be set, the other should be set to NULL (or 0).

If the data sink is undefined the filter output must be explicitly pulled using the `xip_fir_v6_3_data_get` function.

The array is automatically sized by the model given the size of the input request. The owner field of `xip_array_<type>` is ignored and forced to 0.

**Note:** The complex data sink is intended for the Hilbert filter type but is populated for other filter types with `im` set to 0.

## Set Data Handler

```
xip_status
xip_fir_v6_3_set_data_handler(
    xip_fir_v6_3* model,
    xip_array_real_handler data_handler,
    void* handle,
    void* opt_arg
);
```

This function registers a data handler call back function that is called when the output data array is filled following a call to `xip_fir_v6_3_data_send`. The FIR Compiler C model API contains a function, `xip_fir_v6_3_data_send_handler` (see [Send DATA Packet, page 20](#)), to send data to an instance of the model whose signature matches that of a data handler.

The intention of this facility is to enable multiple instances of the model to be chained together such that only the first and last instance of the chain need to be directly controlled using the `xip_fir_v6_3_data_send` and `xip_fir_v6_3_data_get` functions.

The model only supports data handlers for output data arrays of type `xip_array_real` and the value passed to the (`*xip_array_real_handler`) function for the `data` argument is the value set by the `xip_fir_v6_3_set_data_sink` function. See [Type Definitions](#) for details of the data handler function signature. Its arguments are:

1. `data`: A pointer to the `xip_array_real` type containing the data to be processed. The array registered by the `xip_fir_v6_3_set_data_sink` function.
2. `handle`: A void pointer used to point to the next model instance in the filter chain.
3. `opt_arg`: An extra generic argument not currently used by the FIR Compiler C model.

## Calculate Output Size

```
xip_status
xip_fir_v6_3_data_calc_size(
    xip_fir_v6_3* model,
    const xip_array_real* data_in,
    xip_array_real* data_out,
    xip_array_complex* cmplx_data_out
)
xip_status
xip_fir_v6_3_data_calc_size_mpz(
    xip_fir_v6_3* model,
    const xip_array_real* data_in,
    xip_array_mpz* data_out,
    xip_array_mpz_complex cmplx_data_out
)
```

This function calculates the size of an output packet/array given the size of the supplied input packet/array.

The `data_out` or `cmplx_data_out` array dimensions are modified to reflect the size of output the model produces, given the `data_in` array. The array dimensions, `dim` and `data_size` element are updated but the function does not allocate more space. Ensure that the correct amount of space is allocated for the `data` element of the array.

**Note:** Only one of `data_out` or `cmplx_data_out` can be set; the other should be set to NULL (or 0).

## Model Operation Functions

### Send CONFIG Packet

```
xip_status
xip_fir_v6_3_config_send(
    xip_fir_v6_3* model,
    const xip_fir_v6_3_cnfg_packet* cnfg_packet
)
```

This function passes a configuration packet, pointed to by `cnfg_packet` (see [Table 3-5, page 16](#)), to the model. The model implements an internal fifo/queue. A configuration packet is consumed from the queue for every data packet processed, that is, every call to `xip_fir_v6_3_data_send`.

**Note:** If the `fsel` field of the `cnfg_packet` is not sized correctly the function returns `XIP_STATUS_ERROR`.

### Send RELOAD Packet

```
xip_status
xip_fir_v6_3_reload_send(
    xip_fir_v6_3* model,
    const xip_fir_v6_3_rld_packet* rld_packet
)
```

This function passes a reload packet, pointed to by `rld_packet` (see [Table 3-6, page 16](#)), to the model.

**Note:** If the `coeff` field of the `rld_packet` is not sized correctly the function returns `XIP_STATUS_ERROR`.

### Send DATA Packet

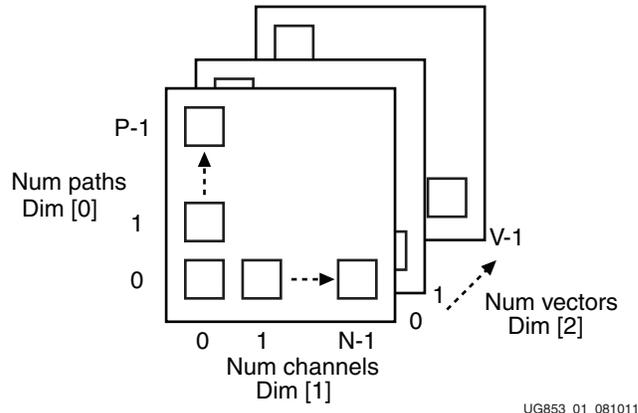
```
xip_status
xip_fir_v6_3_data_send(
    xip_fir_v6_3* model,
    const xip_array_real* data
);
void
xip_fir_v6_3_data_send_handler(
    const xip_array_real* data,
    void* model,
    void* dummy
);
```

This function sends a new data packet, pointed to by `data`, to the model for processing.

The second version of the function, `xip_fir_v6_3_data_send_handler`, is supplied to be used as a (`*xip_array_real_handler`) call back function, see [Set Data Handler, page 19](#) for further details.

Input data is provided using the `xip_array_real` structure pointed to by `data` and is expected to be sized:

*Number of paths x Number of interleaved channels x number of input vectors.*



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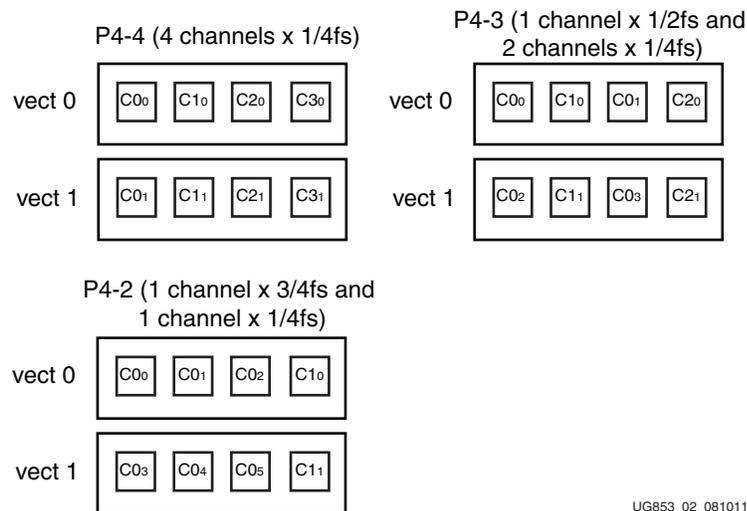
Figure 3-1: Input and Output Data Packet Structure

The 3-D structure illustrated in Figure 3-1 is translated to the 1-D array of the `xip_array_<type>` data element in the order; Paths, Channels, Vectors. The helper functions, `xip_array_<type>_set_chan` (Set Channel, page 13) and `xip_array_<type>_get_chan` (Get Channel, page 14) implement this translation.

The Advanced Channel implementation requires redundant channel positions to be remapped to higher rate channels. The helper functions, `xip_array_<type>_set_chan` (Set Channel, page 13) and `xip_array_<type>_get_chan` (Get Channel, page 14), simplify referencing each channel by presenting a flat index for each channel.

Figure 3-1 illustrates the remapping for three different pattern sequences:

- P4\_4 (4 channels x 1/4fs);
- P4\_3 (1 channel x 1/2fs and 2 channels x 1/4fs);
- P4\_2 (1 channel x 3/4fs and 1 channel x 1/4fs).



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Figure 3-2: Advanced Channel Pattern Data Packet Remapping

## Get DATA Packet

```
xip_status
xip_fir_v6_3_data_get(
    xip_fir_v6_3* model,
    xip_array_real* data,
    xip_array_complex* cmplx_data
);
xip_status
xip_fir_v6_3_data_get_mpz(
    xip_fir_v6_3* model,
    xip_array_mpz* data,
    xip_array_mpz_complex* cmplx_data
);
```

This function retrieves a filtered data packet from the model into the `xip_array_<type>` pointed to by `data` or `cmplx_data`. Only one of `data` or `cmplx_data` maybe set, the other should be set to NULL (or 0).

The size of the array `dim[2]` (Figure 3-1) determines how much data is fetched from the model. If the request is greater than available, then the array size is reduced to reflect this. The model does not modify the amount of space allocated. Both versions of the functions maybe used regardless of the model's internal implementation method. If double data (`xip_real`) is requested when `mpz_t` (`xip_mpz`) has been used internally by the model the output data is truncated, as per the `mpz_get_d` function (see [Ref 3]).

`mpz_t` (`xip_mpz`) is an integer type so the model scales the input data and coefficients by their specified fractional width to use an integer representation. The output is also supplied as an integer value when `mpz_t` is requested. To correctly interpret the `mpz_t` output the model configuration, returned by the `xip_fir_v6_3_get_config` function (see [Get Model Configuration, page 17](#)), should be interrogated to determine the output fractional width.

## Compiling

Compilation of user code requires access to the `fir_compiler_v6_3_bitacc_cmodel.h` header file and the header file of the MPIR [Ref 2] dependent library, `gmp.h`. The header files should be copied to a location where they are available to the compiler. Depending on the location chosen, the 'include' search path of the compiler might need to be modified.

The `fir_compiler_v6_3_bitacc_cmodel.h` header file includes the MPIR header file, so these do not need to be explicitly included in source code that uses the C model. When compiling on Windows, the symbol `NT` must be defined, either by a compiler option, or in user source code before the `fir_compiler_v6_3_bitacc_cmodel.h` header file is included.

## Linking

To use the C model the user executable must be linked against the correct libraries for the target platform.

**Note:** The C model uses the MPIR library. Pre-compiled MPIR libraries are provided with the C model. It is also possible to use GMP or MPIR, libraries from other sources, for example, compiled from source code. For details, see [Dependent Libraries](#).

## Linux

The executable must be linked against the following shared object libraries:

- `libgmp.so.7`
- `libIp_fir_compiler_v6_3_bitacc_cmodel.so`

Using GCC, linking is typically achieved by adding the following command line options:

```
-L. -lgmp -lIp_fir_compiler_v6_3_bitacc_cmodel
```

This assumes the shared object libraries are in the current directory. If this is not the case, the `-L.` option should be changed to specify the library search path to use.

Using GCC, the provided example program `run_bitacc_cmodel.c` can be compiled and linked using the following command:

```
gcc run_bitacc_cmodel.c -o run_bitacc_cmodel -I. -L. -lgmp  
-lIp_fir_compiler_v6_3_bitacc_cmodel
```

**Note:** The C model dynamically links to `gmpxx.so.1` and therefore must be visible to the model while running.

## Windows

The executable must be linked against the following dynamic link libraries:

- `libgmp.dll`
- `libIp_fir_compiler_v6_3_bitacc_cmodel.dll`

Depending on the compiler, the import libraries might also be required:

- `libgmp.lib`
- `libIp_fir_compiler_v6_3_bitacc_cmodel.lib`

Using Microsoft Visual Studio, linking is typically achieved by adding the import libraries to the Additional Dependencies entry under the Linker section of Project Properties.

## Example

The `run_bitacc_cmodel.c` file contains example code to show the basic operation of the C model in various configurations.

## MATLAB Interface

A MEX function and MATLAB<sup>®</sup> software class are provided to simplify the integration with MATLAB. The MEX function provides a low-level wrapper around the underlying C model, while the class file provides a convenient interface to the MEX function.

## Compiling

Source code for a MATLAB MEX function is provided. This can be compiled within MATLAB by changing to the directory that contains the code and running the `make_fir_compiler_v6_3_bitacc_mex.m` script.

## Installation

To use the MEX function, the compiled MEX function must be present on the MATLAB search path. This can be achieved in either of two ways:

1. Add the directory where the compiled MEX function is located to the MATLAB search path (see the MATLAB `addpath` function)
- or
2. Copy the files to a location already on the MATLAB search path.

As with all uses of the C model, the correct C model libraries also need to be present on the platform library search path (that is, `PATH` or `LD_LIBRARY_PATH`).

## MATLAB Class Interface

The `@fir_compiler_v6_3_bitacc` class handles the create/destroy semantics on the C model. The class provides objects for each of the data, configuration and control structures, defined for the C model and previously described in [Structures, page 14](#). All structure elements have MATLAB type double. MATLAB arrays are used with the mapping of types as in [Table 3-7](#).

**Table 3-7: MATLAB to C Model Type Mapping**

| C Model Type             | MATLAB Type                 |
|--------------------------|-----------------------------|
| <code>xip_uint32</code>  | <code>uint32</code>         |
| <code>xip_complex</code> | <code>complex double</code> |
| <code>xip_real</code>    | <code>double</code>         |

The class provides the methods:

### Constructor

```
[model]=fir_compiler_v6_3_bitacc
[model]=fir_compiler_v6_3_bitacc(config)
[model]=fir_compiler_v6_3_bitacc(field, value [, field,value]*)
```

**Note:** \* indicates an optional parameter.

The first version of the function call constructs a model object using the default configuration.

The second version constructs a model object from a structure that specifies the configuration parameter values to use.

The third version is the same as the second, but allows the configuration to be specified as a series of (parameter name, value) pairs rather than a single structure.

The names and valid values of configuration parameters are identical to those previously described for the C model in [Structures, page 14](#).

The MATLAB configuration structure can contain an additional element, `PersistentMemory`. When the element is set to `true` the model's internal data memory state is retained following a call to the [Filter](#) function. Otherwise, the model is [Reset](#) after the filtered data is returned. `PersistentMemory` is set to `false` by default.

## Get Version

```
[version]=get_version(model)
```

This method returns the version string of the C model library used.

## Get Configuration

```
[config]=get_configuration(model)
```

This method returns the current parameters structure of a model object. If the model object is empty, the method returns the default configuration. If the model object has been created, the method returns the configuration parameters that were used to create it.

## Reset

```
[model]=reset(model)
```

This function resets the model, see [Reset Model Object, page 18](#) for further details.

## Send CONFIG Packet

```
[model]=config_send(model, cnfg_packet)
```

This function passes a configuration packet (see [Table 3-5, page 16](#)), to the model. See [Send CONFIG Packet, page 20](#) for further details.

## Send RELOAD Packet

```
[model]=reload_send(model, rld_packet)
```

This function passes a reload packet (see [Table 3-6, page 16](#)), to the model. See [Send RELOAD Packet, page 20](#) for further details.

## Filter

```
[model, data_out]=filter(model, data_in)
```

This function passes a MATLAB double array to the model and returns the filtered output. `data_in` can be a 1, 2 or 3 dimensional array:

- A 1-D array is only supported by a single channel, single path filter configuration.
- A 2-D array is only supported by a multichannel, single path filter configuration.
- All filter configurations support a 3-D array.

See [Send DATA Packet, page 20](#) and [Figure 3-1, page 21](#) for further details on the data array structure.

## Example

The `run_fir_compiler_v6_3_bitacc_mex.m` file contains a MATLAB script with an example of how to run the C model using the MEX function.

To run the sample script:

1. Compile the MEX function with the `make_fir_compiler_v6_3_bitacc_mex.m` script (see [Compiling, page 23](#)).
2. Install the MEX function (see [Installation, page 24](#)).
3. Execute the `run_fir_compiler_v6_3_bitacc_mex.m` script.

## Dependent Libraries

The C model uses MPIR libraries. Pre-compiled MPIR libraries are provided with the C model, using the following versions of the libraries:

- MPIR 2.2.1

Because MPIR is a compatible alternative to GMP, the GMP library can be used in place of MPIR. It is possible to use GMP or MPIR libraries from other sources, for example, compiled from source code.

GMP and MPIR in particular contain many low level optimizations for specific processors. The libraries provided are compiled for a generic processor on each platform, not using optimized processor-specific code. These libraries work on any processor, but run more slowly than libraries compiled to use optimized processor-specific code. For the fastest performance, compile libraries from source on the machine on which you run the executables.

Source code and compilation scripts are provided for the version of MPIR that were used to compile the provided libraries. Source code and compilation scripts for any version of the libraries can be obtained from the GMP [\[Ref 3\]](#) and MPIR [\[Ref 2\]](#) web sites.

**Note:** If compiling MPIR using its configure script (for example, on Linux platforms), use the `--enable-gmpcompat` option when running the configure script. This generates a `libgmp.so` library and a `gmp.h` header file that provide full compatibility with the GMP library.

# Additional Resources

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## Xilinx Resources

For support resources such as Answers, Documentation, Downloads, and Forums, see the Xilinx Support website at:

[www.xilinx.com/support](http://www.xilinx.com/support).

For a glossary of technical terms used in Xilinx documentation, see:

[www.xilinx.com/company/terms.htm](http://www.xilinx.com/company/terms.htm)

## References

1. LogiCORE IP FIR Compiler data sheet [DS795](#)
2. The Multiple Precision Integers and Rationals (MPIR) Library: [www.mpir.org/](http://www.mpir.org/)
3. The GNU Multiple Precision Arithmetic (GMP) Library: [gmplib.org/](http://gmplib.org/)

## Additional Core Resources

For detailed information and updates about the FIR Compiler v6.3 core, see the following document:

- FIR Compiler v6.3 [Release Notes](#)

## Technical Support

For technical support, go to [www.xilinx.com/support](http://www.xilinx.com/support). Questions are routed to a team with expertise using the FIR Compiler v6.3 core.

Xilinx provides technical support for use of this product as described in *FIR Compiler v6.3 Bit Accurate C Model User Guide (UG853)* and the *LogiCORE IP FIR Compiler v6.3 Product Specification (DS795)*. Xilinx cannot guarantee functionality or support of this product for designs that do not follow these guidelines.

